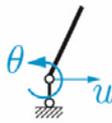
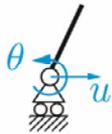
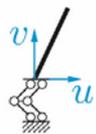
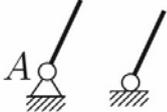
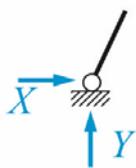
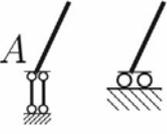
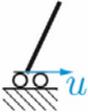
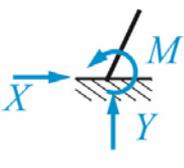
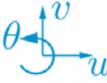
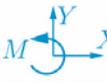
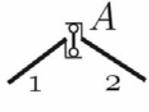
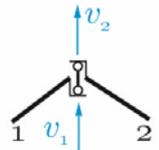
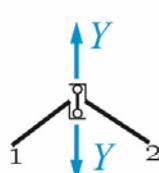
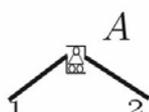
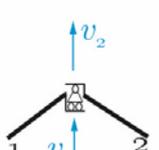
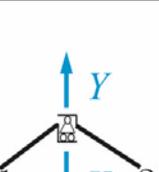
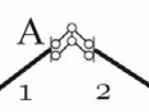
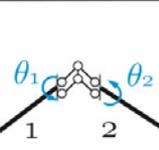
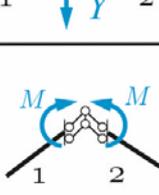
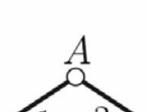
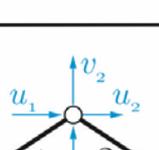
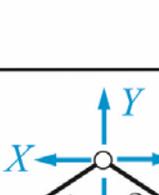
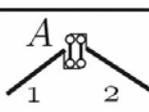
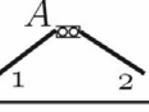
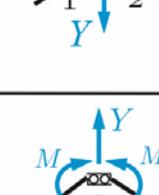
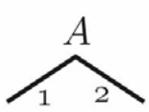
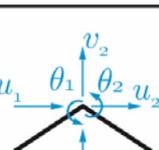
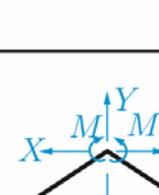


	simbolo	Prestazioni vincoli esterni		m
		 cinematiche (spost. assoluti)	 statiche (reazioni erogate)	
pendolo		 $u_A \neq 0$ $v_A = 0$ $\theta \neq 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A = 0$	1
carrello		 $u_A \neq 0$ $v_A = 0$ $\theta \neq 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A = 0$	1
pantografo		 $u_A \neq 0$ $v_A \neq 0$ $\theta = 0$	 $X_A = 0$ $Y_A = 0$ $M_A \neq 0$	1
cerniera		 $u_A = 0$ $v_A = 0$ $\theta \neq 0$	 $X_A \neq 0$ $Y_A \neq 0$ $M_A = 0$	2
gli fo bipendolo		 $u_A \neq 0$ $v_A = 0$ $\theta = 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A \neq 0$	2
incaastro		 $u_A = 0$ $v_A = 0$ $\theta = 0$	 $X_A \neq 0$ $Y_A \neq 0$ $M_A \neq 0$	3

## Prestazioni cinematiche e statiche dei vincoli interni

	<i>simbolo</i>	<i>Prestazioni vincoli interni</i>		<i>m</i>
		 <i>cinematiche</i> (spost. relativi)	 <i>statiche</i> (reazioni erogate)	
<i>pendolo</i>		 $u_{A2}-u_{A1} \neq 0$ $v_{A2}-v_{A1} = 0$ $\theta_2-\theta_1 \neq 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A = 0$	1
<i>carrello</i>		 $u_{A2}-u_{A1} \neq 0$ $v_{A2}-v_{A1} = 0$ $\theta_2-\theta_1 \neq 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A = 0$	1
<i>pantografo</i>		 $u_{A2}-u_{A1} \neq 0$ $v_{A2}-v_{A1} \neq 0$ $\theta_2-\theta_1 = 0$	 $X_A = 0$ $Y_A = 0$ $M_A \neq 0$	1
<i>cerniera</i>		 $u_{A2}-u_{A1} = 0$ $v_{A2}-v_{A1} = 0$ $\theta_2-\theta_1 \neq 0$	 $X_A \neq 0$ $Y_A \neq 0$ $M_A = 0$	2
<i>gli fo bipendolo</i>	 	 $u_{A2}-u_{A1} \neq 0$ $v_{A2}-v_{A1} = 0$ $\theta_2-\theta_1 = 0$	 $X_A = 0$ $Y_A \neq 0$ $M_A \neq 0$	2
<i>incastro</i>		 $u_{A2}-u_{A1} = 0$ $v_{A2}-v_{A1} = 0$ $\theta_2-\theta_1 = 0$	 $X_A \neq 0$ $Y_A \neq 0$ $M_A \neq 0$	3

COGNOME..... NOME..... MAT.....	PAGINA WEB DEL CORSO: <a href="http://www.pcasini.it/disg/sdc">www.pcasini.it/disg/sdc</a>
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